

Design for Reuse via Structuring Techniques for ASMs

Case Study:

Decomposing and Layering the Java VM

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Composition of ASMs via Standard Refinements

The challenge

Starting point: standard ASMs come with **parallel** execution of **atomic actions** in a **global state** providing

- strong foundational thesis
Yuri Gurevich, ACM TCL 1(1), 2000
- clear notions of state & next-step-function

Goal: incorporate **non atomic structuring** concepts—SEQ, iteration, calling parameterized submachines, returning values, local state, error handling—as **standard refinements** to naturally support

- incremental and modular design of machines
- implementations leading to executable machines

Submachine concepts for reuse in modular design

ASMs with recursive parameterized submachines

$$\overline{\llbracket \text{skip} \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright \emptyset}$$

$$\overline{\llbracket f(t) := s \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright \{(f, a, b)\}}$$

if $a = \llbracket t \rrbracket_{\zeta}^{\mathfrak{A}}$ and $b = \llbracket s \rrbracket_{\zeta}^{\mathfrak{A}}$

$$\frac{\llbracket R \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U \quad \llbracket S \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright V}{\llbracket R S \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U \cup V}$$

$$\frac{\llbracket R \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U}{\llbracket \text{if } \varphi \text{ then } R \text{ else } S \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U}$$

if $\llbracket \varphi \rrbracket_{\zeta}^{\mathfrak{A}} = \text{True}$

$$\frac{\llbracket S \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U}{\llbracket \text{if } \varphi \text{ then } R \text{ else } S \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U}$$

if $\llbracket \varphi \rrbracket_{\zeta}^{\mathfrak{A}} = \text{False}$

$$\frac{\llbracket R \rrbracket_{\zeta \frac{a}{x}}^{\mathfrak{A}} \triangleright U}{\llbracket \text{let } x = t \text{ in } R \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U}$$

if $a = \llbracket t \rrbracket_{\zeta}^{\mathfrak{A}}$

$$\frac{\llbracket R \rrbracket_{\zeta \frac{a}{x}}^{\mathfrak{A}} \triangleright U_a \quad \text{for each } a \in I}{\llbracket \text{forall } x \text{ with } \varphi \text{ do } R \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright \bigcup_{a \in I} U_a}$$

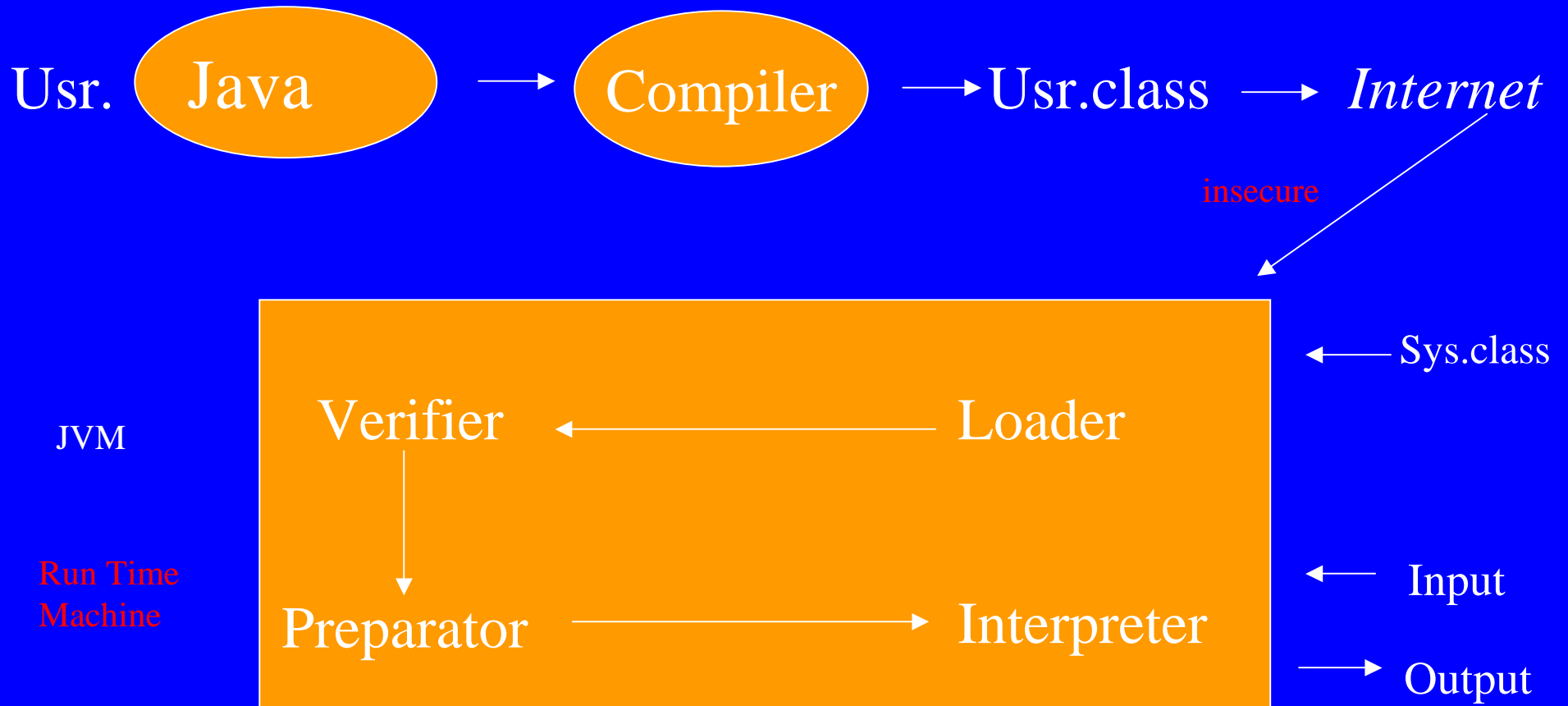
if $I = \{a \in |\mathfrak{A}| : \llbracket \varphi \rrbracket_{\zeta \frac{a}{x}}^{\mathfrak{A}} = \text{True}\}$

$$\frac{\llbracket R \rrbracket_{\zeta \frac{a}{x}}^{\mathfrak{A}} \triangleright U}{\llbracket r(t) \rrbracket_{\zeta}^{\mathfrak{A}} \triangleright U}$$

if $r(x) = R$ is a rule definition
and $a = \llbracket t \rrbracket_{\zeta}^{\mathfrak{A}}$

The Problem

Java/JVM claimed by SUN to be a safe and secure, platform independent programming env for Internet: **correctness problem** for **compiler**, **loader** (name space support), **verifier**, **access right checker** (security manager), **interpreter**.



Goal of the ASM Java/JVM Project

Abstract (platform independent), **rigorous but transparent, modular definition** providing basis for mathematical and experimental **analysis**

- Reflecting SUN's design decisions (faithful ground model)
- Offering correct high-level understanding (to be practically useful for programmers)
- Providing rigorous, implementation independent basis for
 - Analysis and Documentation (for designers) through
 - Mathematical verification
 - Experimental validation
 - Comparison of different implementations
 - Implementation (compiln, loading, bytecode verification, security schemes)

Main Result

A Structured and High-Level Definition of Java
and of its Provably Correct and Secure Implementation
on the Java Virtual Machine

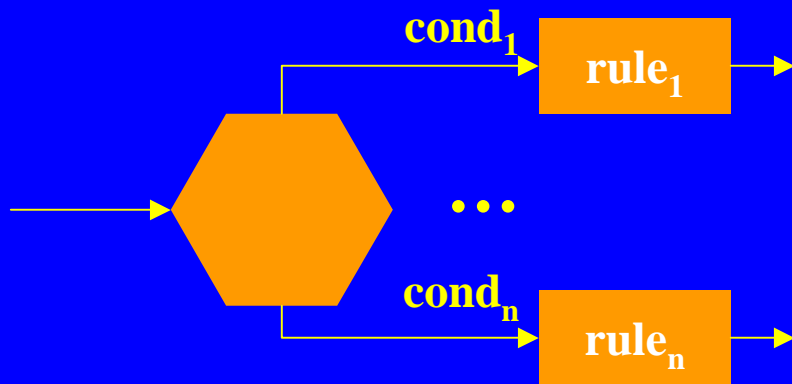
Theorem. Under explicitly stated conditions, any
well-formed and well-typed Java program:

- upon correct compilation
- passes the verifier
- is executed on the JVM
- executes
 - without violating any run-time checks
 - correctly wrt Java source pgm semantics

Decomposition of JVM into Submachines

- **trustfulVM**: defines the execution functionality incrementally from language layered submachines **execVM**, **switchVM**
- **defensiveVM**: defines the verifier functionality, in terms of **trustfulVM** execution, from the language layered submachine **check**; calls **trustfulVM** for execution
- **diligentVM**: checks the constraints at link-time, using a language layered submachine **verifyVM**; calls **trustfulVM** for execution
- **verifyVM** built up from language layered submachines **check**, **propagateVM**, **succ**
- **dynamicVM**: refine **execVM**, **switchVM** by class loading/linking

Diagram notation for Control State ASMs



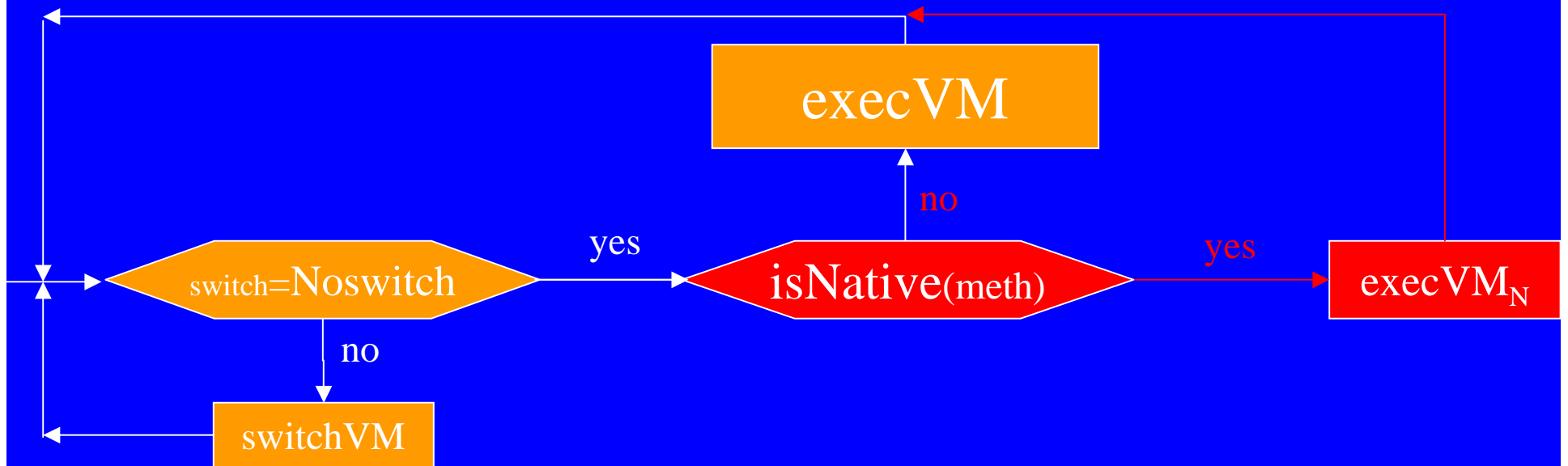
UML: combined
branching/action
nodes

meaning

labeling of the arrows
by “control” states
often suppressed

```
if  $ctl = i$  then
  if  $cond_1$  then  $rule_1$ 
                     $ctl := j_1$ 
                    ...
  if  $cond_n$  then  $rule_n$ 
                     $ctl := j_n$ 
```


Stepwise refinement of trustfulVM

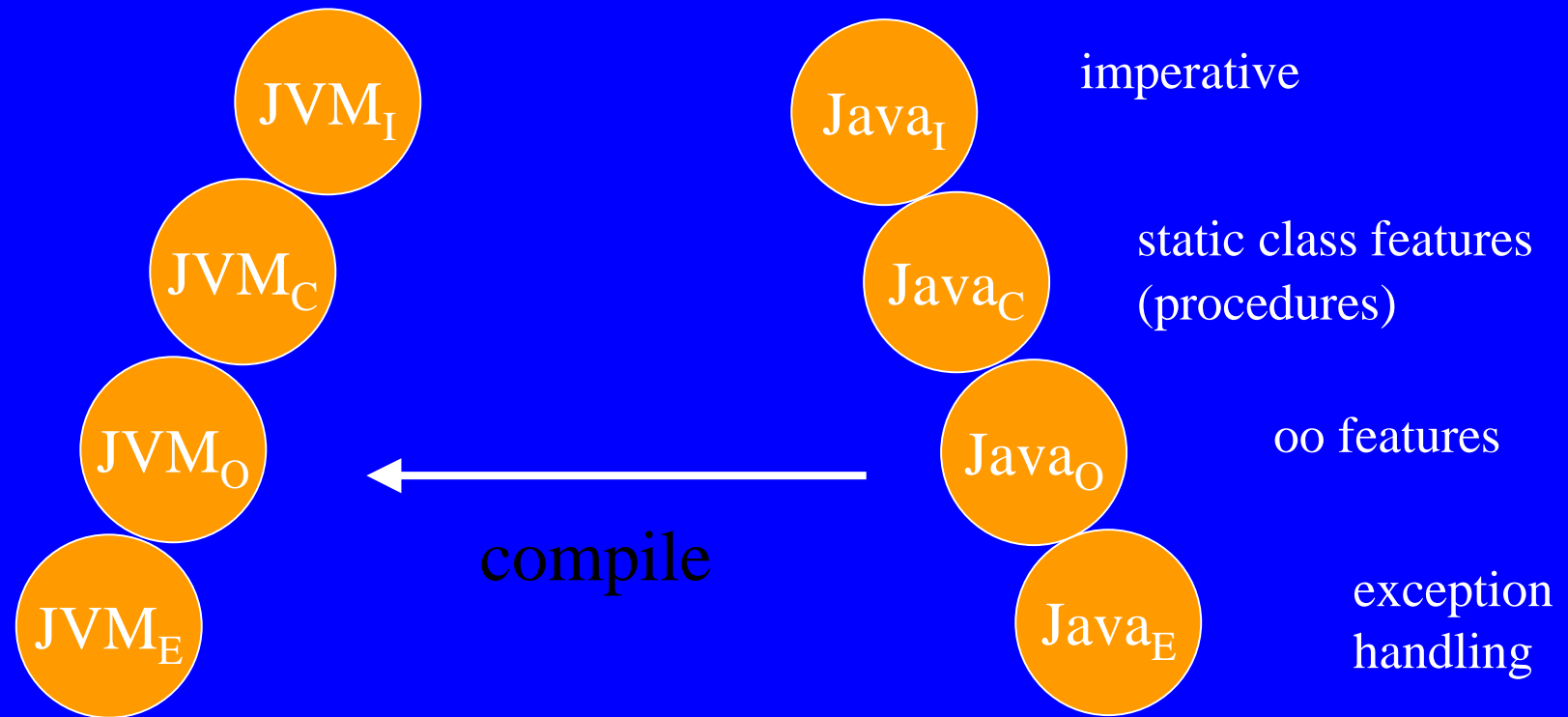


execVM and switchVM incrementally extended (language driven)

trustfulVM_I = execVM_I ⊆ execVM_C ⊆ execVM_O ⊆ execVM_E instructionwise
 defining changes of current frame
 execVM_N ⊆ execVM_D

switchVM_C ⊆ switchVM_E ⊆ switchVM_D defining changes of frame stack
 reflecting meth call/return, class initialization, capturing exceptions
 and class loading/linking

Language driven layering of Java, JVM, compiler



Split into horizontal language components (conservative extensions)

NB. Multiple Threads can be added in a conservative extension Java_T

Language driven decomposition of `execVM` & `switchVM` into parallel trustfulVM submachines

`execVM` = `execVMI`

imperative control constructs

`execVMC`

static class features (modules)

`execVMO`

oo features

`execVME`

exception handling

`execVMN` \subseteq `execVMD`

native JDK library meths (also for load/linking)

`switchVM` = `switchVMC`

method call/return & class initialization

`switchVME`

capturing exceptions

`switchVMD`

loading and linking classes

NB. Grouping similar instructions into one parameterized abstract instr

(expanding type params a locally controllable data/operation refinement)

execVM_I: untyped 32-bit word oriented stack machine supporting exec of compiled while pgm instructions (e.g. purely imperative Java_I pgms)

STATE frame

code: Instr*

pc : Pc

reg: Reg → Word

(local variables)

opd: Word*

meth

Main guard

(suppressed)

halt = undef

**These 7 abstract
instrs comprise
already 150 out
of 200 real JVM
instructions**

case instr of

Prim(p) → **let** (*opd'*, *ws*) = *split*(*opd*, *argSize*(*p*))
 if *p* ∈ *divMod* ⇒ *sndArgIsNotZero*(*ws*) **then**
 opd := *opd'* · *JVMS*(*p*, *ws*)
 pc := *pc* + 1

Dupx(s₁, s₂) → **let** (*opd'*, [*ws*₁, *ws*₂]) = *splits*(*opd*, [*s*₁, *s*₂])
 opd := *opd'* · *ws*₂ · *ws*₁ · *ws*₂
 pc := *pc* + 1

Pop(s) → **let** (*opd'*, *ws*) = *split*(*opd*, *s*)
 opd := *opd'*
 pc := *pc* + 1

Load(t, x) → **if** *size*(*t*) = 1 **then** *opd* := *opd* · [*reg*(*x*)]
 else *opd* := *opd* · [*reg*(*x*), *reg*(*x* + 1)]
 pc := *pc* + 1

Store(t, x) → **let** (*opd'*, *ws*) = *split*(*opd*, *size*(*t*))
 if *size*(*t*) = 1 **then** *reg* := *reg* ⊕ {(*x*, *ws*(0))}
 else *reg* := *reg* ⊕ {(*x*, *ws*(0)), (*x* + 1, *ws*(1))}
 opd := *opd'*
 pc := *pc* + 1

Goto(o) → *pc* := *o*


Cond(p, o) → **let** (*opd'*, *ws*) = *split*(*opd*, *argSize*(*p*))
 opd := *opd'*
 if *JVMS*(*p*, *ws*) **then** *pc* := *o* **else** *pc* := *pc* +

Halt → *halt* := "Halt"

Adding class variables, class initialization, class meth invocation & return

```
execVMC(instr) = cEnv: Class ---> ClassFile providing name, kind,  
execVMI(instr) superclass, implemented interfaces, fields, meths,...  
case instr of  
  GetStatic(−, c/f) → if initialized(c) then  
    opd := opd · globals(c/f)  
    pc := pc + 1  
    else switch := InitClass(c)  
  PutStatic(−, c/f) → if initialized(c) then  
    let (opd', ws) = split(opd, size(c/f))  
    globals(c/f) := ws  
    opd := opd'  
    pc := pc + 1  
    else switch := InitClass(c)  
  InvokeStatic(−, c/m) → if initialized(c) then  
    let (opd', ws) = split(opd, argSize(c/m))  
    opd := opd'  
    switch := Call(c/m, ws)  
    else switch := InitClass(c)  
  Return(t) → let (opd', ws) = split(opd, size(t))  
    switch := Result(ws)
```

Frame stack manipulating submachine (push/pop)

```
switch VMC =  
  case switch of  
    Call(meth, args) → if  $\neg isAbstract(meth)$  then  
      pushFrame(meth, args)  
      switch := Noswitch  
  
    Result(res) → if implicitCall(meth) then popFrame(0, [])  
      else popFrame(1, res)  
      switch := Noswitch  
  
     InitClass(c) → if classState(c) = Linked then  
      classState(c) := Initialized  
      forall  $f \in staticFields(c)$   
        globals(c/f) := default(type(c/f))  
      pushFrame(c/<clinit>())  
      if  $c = Object \vee initialized(super(c))$  then  
        switch := Noswitch  
      else  
        switch := InitClass(super(c))
```

Before its use, after having been loaded & linked (by dynamic VM), a class and its superclasses have to be initialized (implicit call of a **clinit** method upon exec of Put/Get/Invoke)

pushFrame(newMeth, args) =

stack := stack [(pc, reg, opd, meth)

meth := newMeth

pc := 0

reg := makeRegs(args)

opd := []

popFrame(offset; result) =

let (stack*; [(pc*; reg*; opd*; meth*)]) =

split (stack; 1)

pc := pc* + offset

reg := reg*

opd := opd* . result

meth := meth*

stack := stack*

Instance creation/initialization, access, methods, type casts

```
execVMO(instr) =  
execVMC(instr)  
case instr of
```

```
  New(c) →
```

```
    if initialized(c) then create r
```

```
      heap(r) := Object(c, {(f, defaultVal(f)) | f ∈ instanceFields(c)})
```

```
      opd := opd · [r]
```

```
      pc := pc + 1
```

```
    else switch := InitClass(c)
```

```
  GetField(┐, c/f) → let (opd', [r]) = split(opd, 1)
```

```
    if r ≠ null then
```

```
      opd := opd' · getField(r, c/f)
```

```
      pc := pc + 1
```

```
  PutField(┐, c/f) → let (opd', [r] · ws) = split(opd, 1 + size(c/f))
```

```
    if r ≠ null then
```

```
      setField(r, c/f, ws)
```

```
      pc := pc + 1
```

```
      opd := opd'
```

```
  InvokeSpecial(┐, c/m) →
```

```
    let (opd', [r] · ws) = split(opd, 1 + argSize(c/m))
```

```
    if r ≠ null then
```

```
      opd := opd'
```

```
      switch := Call(c/m, [r] · ws)
```

```
  InvokeVirtual(┐, c/m) →
```

```
    let (opd', [r] · ws) = split(opd, 1 + argSize(c/m))
```

```
    if r ≠ null then
```

```
      opd := opd'
```

```
      switch := Call(lookup(classOf(r), c/m), [r] · ws)
```

```
  InstanceOf(c) → let (opd', [r]) = split(opd, 1)
```

```
    opd := opd' · (r ≠ null ∧ classOf(r) ⊆ c)
```

```
    pc := pc + 1
```

```
  Checkcast(c) → let r = top(opd)
```

```
    if r = null ∨ classOf(r) ⊆ c then
```

```
      pc := pc + 1
```

heap: Ref ---> Object (Class, Map (Class/Field, Val))

Ref ⊆ Word

Instance method calls with
- **early binding**: InvokeSpecial,
where the method reference
contains the class of the
implementing method
- **late binding**: Invoke Virtual,
where the implementing
method is looked up
dynamically

`execVME`: adding the effect of exception handling instructions upon the current frame

`execVMO(instr)`

case `instr` **of**

`Athrow` \rightarrow **let** `[r]` = `take(opd, 1)`
 if `r` \neq `null` **then** `switch := Throw(r)`
 else `raise("NullPointerException")`

`Jsr(s)` \rightarrow `opd := opd · [pc + 1]`
 `pc := s`

`Ret(x)` \rightarrow `pc := reg(x)`

`Prim(p)` \rightarrow **let** `ws = take(opd, argSize(p))`
 if `p` \in `divMod` \wedge `sndArgIsZero(ws)` **then**
 `raise("ArithmeticException")`

`GetField(–, c/f)` \rightarrow **let** `[r]` = `take(opd, 1)`
 if `r` = `null` **then** `raise("NullPointerException")`

`PutField(–, c/f)` \rightarrow **let** `[r] · ws = take(opd, 1 + size(c/f))`
 if `r` = `null` **then** `raise("NullPointerException")`

`InvokeSpecial(–, c/m)` \rightarrow
 let `[r] · ws = take(opd, 1 + argSize(c/m))`
 if `r` = `null` **then** `raise("NullPointerException")`

`InvokeVirtual(–, c/m)` \rightarrow
 let `[r] · ws = take(opd, 1 + argSize(c/m))`
 if `r` = `null` **then** `raise("NullPointerException")`

`Checkcast(c)` \rightarrow **let** `r = top(opd)`
 if `r` \neq `0` \wedge $\neg(\text{classOf}(r) \sqsubseteq c)$ **then**
 `raise("ClassCastException")`

Instructions to

- raise an exception
- jump to subroutine
- return from subroutine

Run-time exceptions

`raise(c)` defined e.g. by
`switch:=Call(fail(c), [])`

Adding frame stack manipulations for exceptions

Java try/catch implemented by tables of exceptions

(from, upto, handle, type)

```
switch VME =  
  switch VMC  
  case switch of  
    Call(meth, args) → if isAbstract(meth) then  
                        raise( "AbstractMethodError" )  
    InitClass(c) → if unusable(c) then  
                   raise( "NoClassDefFoundError" )  
    Throw(r) → if ¬escapes(meth, pc, classOf(r)) then  
                let exc = handler(meth, pc, classOf(r))  
                  pc := handle(exc)  
                  opd := [r]  
                  switch := Noswitch  
                else  
                  if methNm(meth) = "<clinit>" then  
                    if ¬(classOf(r) ≤h Error) then  
                      raise( "ExceptionInInitializerError" )  
                      pc := undef  
                    else switch := ThrowInit(r)  
                  else popFrame(0, [])  
    ThrowInit(r) → let c = classNm(meth)  
                   classState(c) := Unusable  
                   popFrame(0, [])  
                   if ¬superInit(top(stack), c) then  
                     switch := Throw(r)
```

searching exc table
of current method
for handler

continue searching
exc table of invoker

class becomes unusable
when clinit exc not caught
(recursively)

```
superInit((-, -, -, m), c) =  
  methNm(m) = "<clinit>" ∧ super(classNm(m)) = c
```

Specify Native Methods of JDK Libraries: 2 Exls

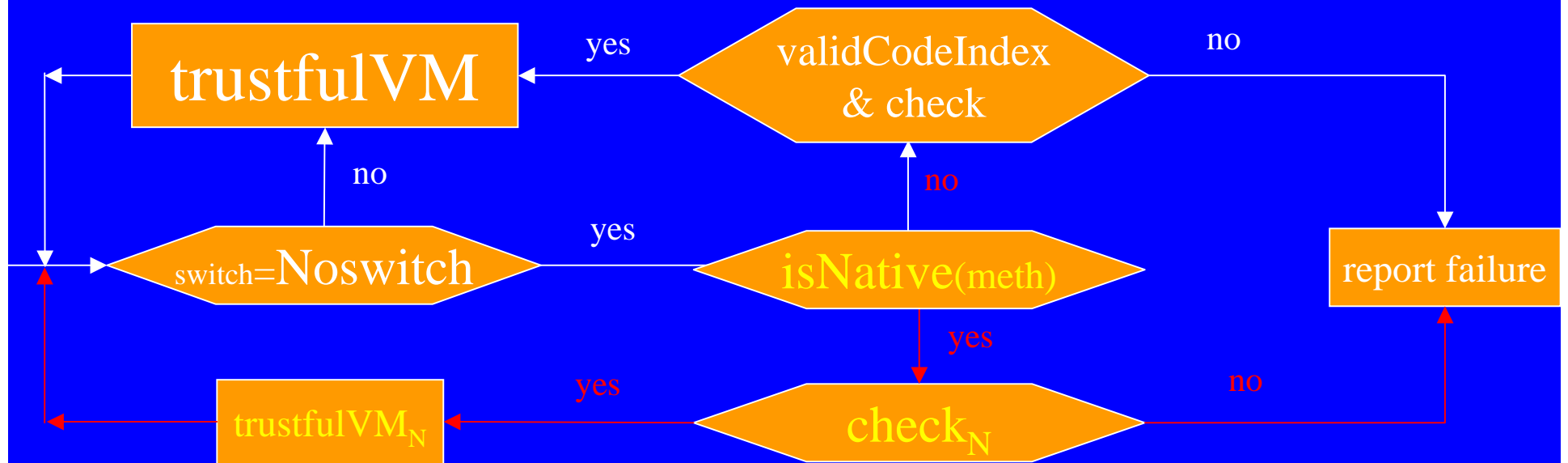
```
exec VMN =  
  if meth = Object/equals then  
    switch := Result(reg(0) = reg(1))  
  elseif meth = Object/clone then  
    let r = reg(0)  
    if classOf(r)  $\preceq_h$  Cloneable then  
      create r'  
      heap(r') := heap(r)  
      switch := Result(r')  
    else  
      raise( "CloneNotSupportedException" )
```

Executable version contains other native methods
e.g. for loading and resolving classes and for
newInstance to create an instance for a given class
object (see the extension execVM_D of VM_N below)

Deriving the Bytecode Verifier Conditions from Type Checking Runtime Constraints

- **Defensive VM:** Checks at run-time, before every execution step, the “structural constraints” which describe the verifier functionality (restrictions on run-time data: argument types, valid Ret addresses, resource bounds,...) guaranteeing “safe” execution
- **Static constraints (well-formedness) checked at link-time.**
- **Theorem:** If Defensive VM executes P successfully, then so does Trustful VM, with the same semantical effect.

Stepwise refinement of defensive VM



check incrementally extended, language layered as for trustfulVM

i.e. $check_I$ extended by $check_C$

extended by $check_O$

extended by $check_E$

extended by $check_N$

extended by $check_D$

Lifting execVM to reg and opd types

Checking conditions formulated in terms of value types, so that they can be lifted from run-time to link-time checks

Words/word fcts refined by type information, yielding (val,typ) pairs

JVM weakly typed: reg/opd locations can hold int, float, low/high word of long or double

type frames (type(reg), type(opd)) where type selects types

Primops executed with right no/types of args, no opd over/underflow, double words not swapped/operated componentwise, locvars assigned when accessed

g. 15.2 Checking JVM_T instructions

$check_I(instr, maxOpd, pc, regT, opdT) =$

case instr of

$Prim(p) \rightarrow opdT \sqsubseteq_{suf} argTypes(p) \wedge$
 $\neg overflow(maxOpd, opdT, retSize(p) - argSize(p))$

$Dupx(s_1, s_2) \rightarrow \mathbf{let} [ts_1, ts_2] = tops(opdT, [s_1, s_2])$
 $length(opdT) \geq s_1 + s_2 \wedge$
 $\neg overflow(maxOpd, opdT, s_2) \wedge$
 $validTypeSeq(ts_1) \wedge validTypeSeq(ts_2)$

$Pop(s) \rightarrow length(opdT) \geq s$

$Load(t, x) \rightarrow$

if $size(t) = 1$ **then** $[regT(x)] \sqsubseteq_{mv} t \wedge \neg overflow(maxOpd, opdT, 1)$

else $[regT(x), regT(x + 1)] \sqsubseteq_{mv} t \wedge \neg overflow(maxOpd, opdT, 2)$

$Store(t, -) \rightarrow opdT \sqsubseteq_{suf} t$

$Goto(o) \rightarrow True$

$Cond(p, o) \rightarrow opdT \sqsubseteq_{suf} argTypes(p)$

$Halt \rightarrow True$

$validTypeSeq([])$

$validTypeSeq([t]) = \text{not isHigh}(t)$

$validTypeSeq([]) = \text{not isHigh}(t)$

$\text{isHigh}(t) = (t = \text{highLong} \text{ or}$

$t = \text{highDouble})$

$[\text{single}] \sqsubseteq_{mv} \text{single}$ (for single = int, float)

$[\text{lowLD}, \text{highLD}] \sqsubseteq_{mv} \text{LD}$

for LD = Long, Double

\sqsubseteq_{mv} condition implies: a) $reg(x)$ is assigned ($regT(x) \neq \text{undef}$) when accessed
 b) stored double words have correct low/high types

Checking JVM_C instructions for types of class fields and of method invocation arguments/results

- a) types of values put into class fields are compatible with their declared types
- b) types of actual args in class meth invocations are compatible with formal params
- c) type of any returned result is compatible with the return type of the method, which in turn is compatible with the move type as specified by the instruction parameter

$check_C(meth)(instr, maxOpd, pc, regT, opdT) =$
 $check_I(instr, maxOpd, pc, regT, opdT) \vee$

case instr of

$GetStatic(t, c/f) \rightarrow \neg overflow(maxOpd, opdT, size(t))$

$PutStatic(t, c/f) \rightarrow opdT \sqsubseteq_{suf} t$

$InvokeStatic(t, c/m) \rightarrow opdT \sqsubseteq_{suf} argTypes(c/m) \wedge$
 $\neg overflow(maxOpd, opdT, size(t) -$
 $argSize(c/m))$

$Return(t) \rightarrow opdT \sqsubseteq_{suf} returnType(meth) \wedge$
 $returnType(meth) \sqsubseteq_{mv} t$

$\square \sqsubseteq_{mv} void$

See later refinement by endinit for returns from instance initializn methods

fig. 15.4 Checking JVM₀ instructions

Constraint on initializn status (in regT(0)) upon return from an init

$check_O(meth)(instr, maxOpd, pc, regT, opdT) =$
 $check_C(meth)(instr, maxOpd, pc, regT, opdT) \wedge endinit(meth, instr, regT)$
case instr of
New(c) $\rightarrow \neg overflow(maxOpd, opdT, 1)$
GetField(t, c/f) $\rightarrow opdT \sqsubseteq_{suf} c \wedge \neg overflow(maxOpd, opdT, size(t) - 1)$
PutField(t, c/f) $\rightarrow opdT \sqsubseteq_{suf} c \cdot t$ target ref type is initd subtype of param
InvokeSpecial(_, c/m) \rightarrow
 let [c'] · _ = *take*(opdT, 1 + *argSize*(c/m))
 length(opdT) > *argSize*(c/m) \wedge
 opdT \sqsubseteq_{suf} *argTypes*(c/m) \wedge
 $\neg overflow(maxOpd, opdT, retSize(c/m) - argSize(c/m) - 1) \wedge$
 if *methNm*(m) = "<init>" **then**
 initCompatible(meth, c', c) Constraint on constructor invokations
 else c' \sqsubseteq c on un-/partially initialized objects
InvokeVirtual(_, c/m) \rightarrow
 opdT \sqsubseteq_{suf} c · *argTypes*(c/m) \wedge
 $\neg overflow(maxOpd, opdT, retSize(c/m) - argSize(c/m) - 1)$
InstanceOf(c) $\rightarrow opdT \sqsubseteq_{suf}$ Object top of opd stack has initialized ref type
Checkcast(c) $\rightarrow opdT \sqsubseteq_{suf}$ Object

Updating initState of objects in switchVM upon calling instance initialization meths along class hierarchy (only upon un-initialized or partially initialized objects)

Fig. 15.5 Pushing a new JVM₀ frame

```
pushFrame(c/m, args) =  
  stack := stack · [(pc, reg, opd, meth)]  
  meth := c/m  
  pc := 0  
  opd := []  
  reg := makeRegs(args)  
  if methNm(m) = "<init>" then  
    let [r] · _ = args  
    if c = Object then  
      initState(r) := Complete  
    else  
      initState(r) := InInit
```

A newly created object of class *c* is considered as un-initialized, reflected by setting *initState*(*r*):= *New*(*pc*) upon executing the instr *New*(*c*) in *execVM*₀

To guarantee: Athrow only applied upon throwable objects

Pgm counter values always denote valid addresses

§. 15.6 Checking JVM_E instructions

$$check_E(meth)(instr, maxOpd, pc, regT, opdT) =$$
$$check_O(meth)(instr, maxOpd, pc, regT, opdT) \vee$$

case *instr* of

$$Store(\mathbf{addr}, x) \rightarrow length(opdT) > 0 \wedge isRetAddr(top(opdT))$$
$$Athrow \rightarrow opdT \sqsubseteq_{suf} \mathbf{Throwable}$$
$$Jsr(o) \rightarrow \neg overflow(maxOpd, opdT, 1)$$
$$Ret(x) \rightarrow isRetAddr(regT(x))$$
$$isRetAddr(\mathbf{retAddr}(-)) = True$$
$$isRetAddr(-) = False$$

In execVM_E refine Jsr(s) to record that a retAddr is pushed on stack:
opd := opd · [(pc+1, retAddr(s))]
pc := s

No computed gotos: only Jsr generates retAddr & pushes them on stack

only Store can move a retAddr into a register

Checking native meths: 2 Exls

- Check guarantees that the VM has native code for the meth to execute upon its call
- Exls: equal and clone

$\text{check}_N(c/m) =$

$c/m = \text{Object/equals}$ or $c/m = \text{Object/clone}$

- Implementation must assure that return val of native meths is of correct return type (bytecode verifier cannot check this, although it can be checked at run-time)

Bytecode Type Assignments

- Link-time verifiable **type assignments** (conditions) extracted from **checking** function of the Defensive VM

Main problem: return addresses of Jsr(s), reached using Ret(x)

- **Soundness Theorem**: If P satisfies the type assignment conditions, then Defensive VM executes P without violating any run-time check.

Proof by induction on runs of the Defensive VM

- **Completeness Theorem**: Bytecode generated by **compile** from a legal Java program does have type assignments.

Inductive proof introduces **certifying compiler** assigning to each byte code instr also a type frame, which then can be shown to constitute a type assignment for the compiled code

Type assignments without subroutine call stacks

Definition 16.3.8 (Bytecode type assignment). A bytecode type assignment with domain \mathcal{D} for a method μ is a family $(regT_i, opdT_i)_{i \in \mathcal{D}}$ of type frames satisfying the following conditions:

type frames assigned only to valid code indices (not necessarily to all of them)

- T1. \mathcal{D} is a set of valid code indices of the method μ .
- T2. Code index 0 belongs to \mathcal{D} .
- T3. Let $[\tau_1, \dots, \tau_n] = argTypes(\mu)$ and $c = classNm(\mu)$. If μ is a
 - a) class initialization method: $regT_0 = \emptyset$.
 - b) class method: $\{0 \mapsto \tau_1, \dots, n-1 \mapsto \tau_n\} \sqsubseteq_{reg} regT_0$.
 - c) instance method: $\{0 \mapsto c, 1 \mapsto \tau_1, \dots, n \mapsto \tau_n\} \sqsubseteq_{reg} regT_0$.
 - d) constructor: $\{0 \mapsto InInit, 1 \mapsto \tau_1, \dots, n \mapsto \tau_n\} \sqsubseteq_{reg} regT_0$.
- T4. The list $opdT_0$ is empty.
- T5. If $i \in \mathcal{D}$, then $check(\mu, i, regT_i, opdT_i)$ is true.
- T6. If $i \in \mathcal{D}$ and $(j, regS, opdS) \in succ(\mu, i, regT_i, opdT_i)$, then $j \in \mathcal{D}$, $regS \sqsubseteq_{reg} regT_j$ and $opdS \sqsubseteq_{seq} opdT_j$.
- T7. If $i \in \mathcal{D}$, $code(i) = Ret(x)$ and $regT_i(x) = retAddr(s)$, then for all reachable $j \in \mathcal{D}$ with $code(j) = JsR(s)$:
 - a) $j+1 \in \mathcal{D}$,
 - b) $regT_i \sqsubseteq_{reg} mod(s) \triangleleft regT_{j+1}$,
 - c) $opdT_i \sqsubseteq_{seq} opdT_{j+1}$,
 - d) $regT_j \sqsubseteq_{reg} mod(s) \triangleleft regT_{j+1}$,
 - e) if $retAddr(l)$ occurs in $mod(s) \triangleleft regT_{j+1}$, then each code index which belongs to s belongs to l ,
 - f) neither $(c, k)_{new}$ nor $InInit$ occur in $mod(s) \triangleleft regT_{j+1}$.
- T8. If $i \in \mathcal{D}$ and $retAddr(s)$ occurs in $regT_i$, then i belongs to s .
If $i \in \mathcal{D}$ and $retAddr(s)$ occurs in $opdT_i$, then $i = s$.

initial type frame, assigned to 0: declared meth arg types more specific than the types in $regT_0$ (this in reg_0 of meth class type c & partly initlized by constr) opd is empty

successor type frame more specific than type frame assigned to succ index

Assume: a) compiled finally code is connected
b) subroutine starts with a Store(addr,x)

used for return by Ret(x)

retAddrs occur in regs only within subroutines, on stack only at its start

Type frames assigned to valid indices: conditions at 0 and at successors

Definition 16.3.8 (Bytecode type assignment). A bytecode type assignment with domain \mathcal{D} for a method μ is a family $(regT_i, opdT_i)_{i \in \mathcal{D}}$ type frames satisfying the following conditions:

- T1. \mathcal{D} is a set of valid code indices of the method μ .
- T2. Code index 0 belongs to \mathcal{D} .
- T3. Let $[\tau_1, \dots, \tau_n] = argTypes(\mu)$ and $c = classNm(\mu)$. If μ is a
 - a) class initialization method: $regT_0 = \emptyset$.
 - b) class method: $\{0 \mapsto \tau_1, \dots, n-1 \mapsto \tau_n\} \sqsubseteq_{reg} regT_0$.
 - c) instance method: $\{0 \mapsto c, 1 \mapsto \tau_1, \dots, n \mapsto \tau_n\} \sqsubseteq_{reg} regT_0$.
 - d) constructor: $\{0 \mapsto InInit, 1 \mapsto \tau_1, \dots, n \mapsto \tau_n\} \sqsubseteq_{reg} regT_0$.
- T4. The list $opdT_0$ is empty.
- T5. If $i \in \mathcal{D}$, then $check(\mu, i, regT_i, opdT_i)$ is true.
- T6. If $i \in \mathcal{D}$ and $(j, regS, opdS) \in succ(\mu, i, regT_i, opdT_i)$, then $j \in \mathcal{D}$, $regS \sqsubseteq_{reg} regT_j$ and $opdS \sqsubseteq_{seq} opdT_j$.

Type frames have to satisfy the check conditions

Subroutine type frame conditions upon return to successor of reachable subroutine caller: type of **local variables** to be used at successor $j+1$ is less specific there than at return point i - if modified by the subroutine - , at caller j otherwise; type of **opd** at return point is more specific than at continuation point $j+1$

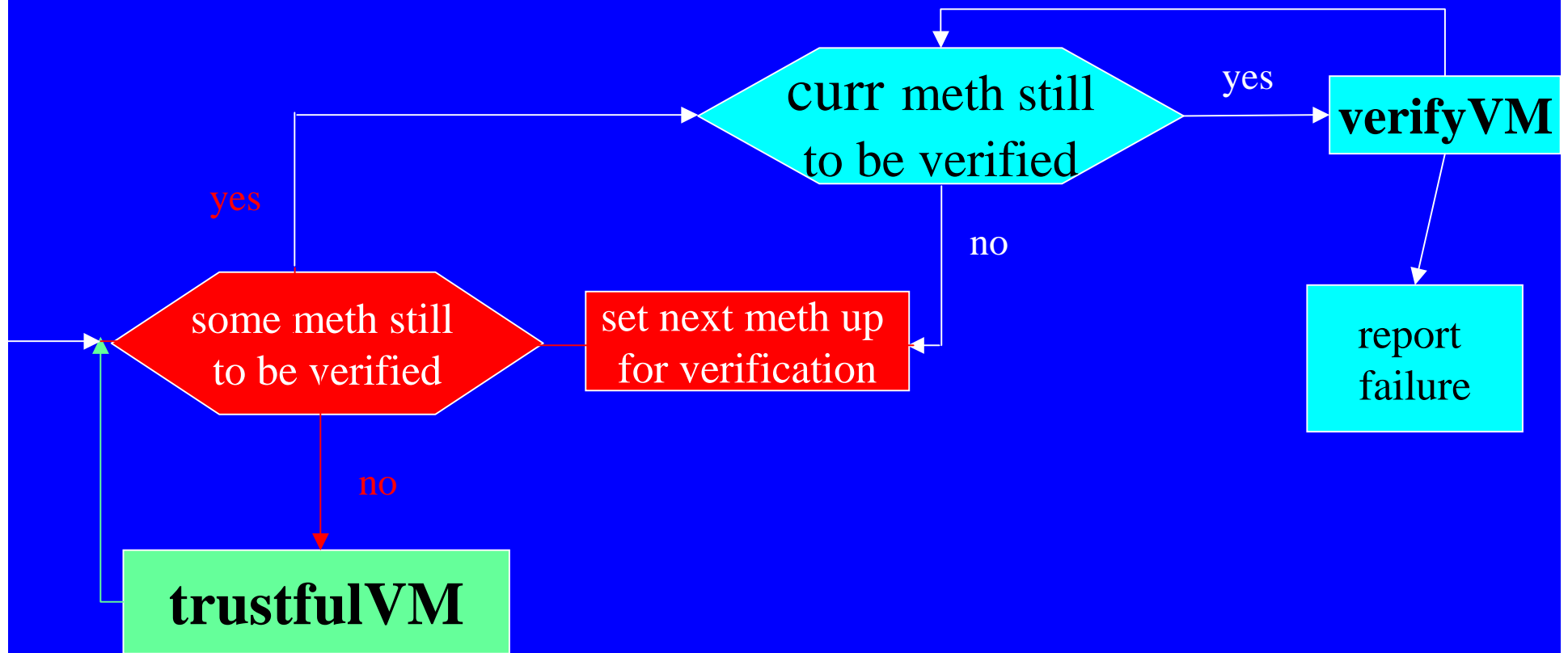
T7. If $i \in \mathcal{D}$, $code(i) = Ret(x)$ and $regT_i(x) = retAddr(s)$, then for all reachable $j \in \mathcal{D}$ with $code(j) = Jsr(s)$:

- a) $j + 1 \in \mathcal{D}$, successor index of subroutine caller is valid
- b) $regT_i \sqsubseteq_{reg} mod(s) \triangleleft regT_{j+1}$,
- c) $opdT_i \sqsubseteq_{seq} opdT_{j+1}$,
- d) $regT_j \sqsubseteq_{reg} mod(s) \triangleleft regT_{j+1}$,
- e) if $retAddr(l)$ occurs in $mod(s) \triangleleft regT_{j+1}$, then each code index which belongs to s belongs to l ,
- f) neither $(c, k)_{new}$ nor $InInit$ occur in $mod(s) \triangleleft regT_{j+1}$.

e) **Proper nesting of subroutines**: a $retAddr$ occurring at succ of caller of a subroutine, which did not modify it, is addr of an enclosing subroutine

f) no not fully initialized object can be used at succ of caller of a subroutine without having been modified by the subroutine (guarantees that there is at most one type $(c, k)_{new}$ & prevents double initialization)

Stepwise refinement of diligent $VM_{I,C,O,E}$



switch VM_C in trustfulVM is refined to also link classes before their initialization, where the linking submachine triggers verifyVM

verifyVM built out of langg layered check, succ, propagate

The state of the verifier

$\text{regV}_i, \text{opdV}_i$ to store register and opd stack types computed for instr i
Initially $\text{opdV}_0 = []$, $\text{regV}_0 = \text{types of meth args and target ref}$, otherwise undefined

$\text{visited}(i)$ indicating that to instr i a type frame has been associated

$\text{changed}(i)$ for instrs i whose type frame has still to be checked before
being propagated to successors

Initially $\text{changed}_0 = \text{visited}_0 = \text{true}$, otherwise undef

$\text{verifyMeths: Class/MSig}^*$ $\text{meth}_v = \text{top}(\text{verifyMeths})$ verifyClass

Def: some method still to be verified iff $\text{verifyMeths} \neq []$

curr method still to be verified iff $\text{dom}(\text{changed}) \neq \emptyset$

report failure = (halt := FailureReport)

For correct propagation of type frames upon return from subroutines, two fcts **enterJsr** and **leaveJsr** are needed to record visited code indices where a subroutine has been entered or exited

Macros for initializing VerifyVM

set next meth up for verification

```
let verifyMeths' = drop(verifyMeths, 1)
```

```
  verifyMeths := verifyMeths'
```

```
  if length(verifyMeths') > 0 then
```

```
    initVerify(top(verifyMeths'))
```

```
  else
```

```
    classState(verifyClass) := Linked
```

```
initVerify(meth)
```

```
  visited(0) := True
```

```
  changed(0) := True
```

```
  regV0 := formals(meth)
```

```
  opdV0 := [ ]
```

```
  forall i ∈ dom(visited), i ≠ 0
```

```
    visited(i) := undef
```

```
    changed(i) := undef
```

```
    regVi := undef
```

```
    opdVi := undef
```

Type correctness of meth invocation is guaranteed by `formals (meth)`, which initially assigns to the type registers the arg types of the meth and for inst meths/constructors also the type of the target reference (i.e. the class of the meth or `InInit`)

Linking classes before their initialization triggers their verification

switch VM_C is extended by the rule

case switch of

$InitClass(c) \rightarrow$ if $classState(c) = Referenced$ then $linkClass(c)$

$linkClass(c) =$

let $classes = \{super(c)\} \cup implements(c)$

if $c = Object \vee \forall c' \in classes : classState(c') \geq Linked$ **then**

$prepareVerify(c)$

elseif $\neg cyclicInheritance(c)$ **then**

choose $c' \in classes, classState(c') = Referenced$

$linkClass(c')$

else

$halt := "Cyclic Inheritance: " \cdot classNm(c)$

This recursive submachine terminates since the class inheritance hierarchy is finite

The preparatory test checks the class format of the class file and the static constraints for the method bodies

```

prepareVerify(c) =
  if constraintViolation(c) then
    halt := violationMsg(classNm(c))
  else
    let verifyMeths' = [(c/m) | m ∈ dom(methods(cEnv(c))),
                        ¬null(code(c/m))]
    verifyMeths := verifyMeths'
    verifyClass := c
    initVerify(top(verifyMeths'))
    prepareClass(c)

```

constraintViolation checks class file format and other static conditions imposed on the method bodies

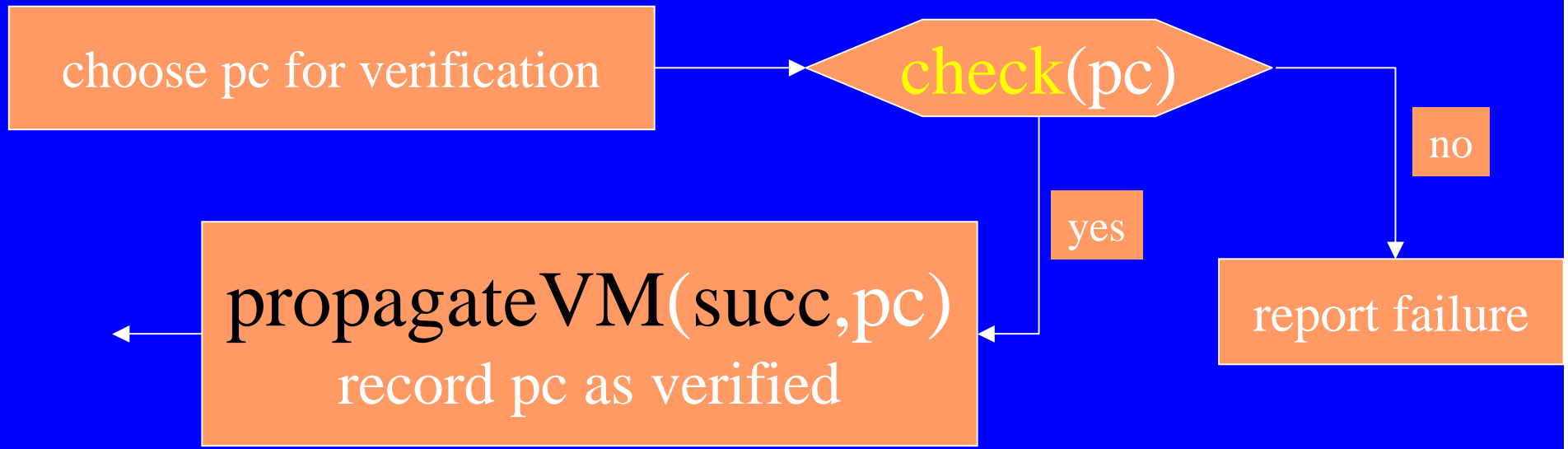
Class preparation macro to create and initialize static fields

```

prepareClass(c) =
  forall f ∈ staticFields(c)
    globals(c/f) := defaultVal (type(c/f))

```

Stepwise refinement of $\text{verifyVM}_{I,C,O,E}$



Defn. choose pc for verification = choose $pc \in \text{dom}(\text{changed})$
record pc as verified = $(\text{changed}(pc) := \text{undef})$

propagate VM the checked type frame from pc to all possible successor frames, simulating execVM on types frames

Stepwise refinement: $\text{propagate}_I \subseteq \text{propagate}_E$

(no propagation for native meths) $\text{succ}_I \subseteq \text{succ}_C \subseteq \text{succ}_O \subseteq \text{succ}_E$

Fig. 16.12 Successors for JVM_I instructions

$$\begin{aligned}
 \text{succ}_I(\text{instr}, pc, \text{reg}T, \text{opd}T) = & \\
 \text{case } \text{instr} \text{ of} & \\
 \text{Prim}(p) \rightarrow & \{(pc + 1, \text{reg}T, \text{drop}(\text{opd}T, \text{argSize}(p)) \cdot \text{returnType}(p))\} \\
 \text{Dupx}(s_1, s_2) \rightarrow & \\
 & \{(pc + 1, \text{reg}T, \text{drop}(\text{opd}T, s_1 + s_2) \cdot \\
 & \quad \text{take}(\text{opd}T, s_2) \cdot \text{take}(\text{opd}T, s_1 + s_2))\} \\
 \text{Pop}(s) \rightarrow & \{(pc + 1, \text{reg}T, \text{drop}(\text{opd}T, s))\} \\
 \text{Load}(t, x) \rightarrow & \\
 & \text{if } \text{size}(t) = 1 \text{ then} \\
 & \quad \{(pc + 1, \text{reg}T, \text{opd}T \cdot [\text{reg}T(x)])\} \\
 & \text{else} \\
 & \quad \{(pc + 1, \text{reg}T, \text{opd}T \cdot [\text{reg}T(x), \text{reg}T(x + 1)])\} \\
 \text{Store}(t, x) \rightarrow & \\
 & \text{if } \text{size}(t) = 1 \text{ then} \\
 & \quad \{(pc + 1, \text{reg}T \oplus \{(x, \text{top}(\text{opd}T))\}, \text{drop}(\text{opd}T, 1))\} \\
 & \text{else} \\
 & \quad \{(pc + 1, \text{reg}T \oplus \{(x, t_0), (x + 1, t_1)\}, \text{drop}(\text{opd}T, 2))\} \\
 & \text{where } [t_0, t_1] = \text{take}(\text{opd}T, 2) \\
 \text{Goto}(o) \rightarrow & \{(o, \text{reg}T, \text{opd}T)\} \\
 \text{Cond}(p, o) \rightarrow & \{(pc + 1, \text{reg}T, \text{drop}(\text{opd}T, \text{argSize}(p))), \\
 & \quad (o, \text{reg}T, \text{drop}(\text{opd}T, \text{argSize}(p)))\}
 \end{aligned}$$

Extending successor type frames by simuln of execVM_C instrs

. 16.13 Successors for JVM_C instructions

$\text{succ}_C(\text{meth})(\text{instr}, \text{pc}, \text{regT}, \text{opdT}) =$

$\text{succ}_I(\text{instr}, \text{pc}, \text{regT}, \text{opdT}) \cup$

case instr of

$\text{GetStatic}(t, c/f) \rightarrow \{(pc + 1, \text{regT}, \text{opdT} \cdot t)\}$

$\text{PutStatic}(t, c/f) \rightarrow \{(pc + 1, \text{regT}, \text{drop}(\text{opdT}, \text{size}(t)))\}$

$\text{InvokeStatic}(t, c/m) \rightarrow \{(pc + 1, \text{regT}, \text{drop}(\text{opdT}, \text{argSize}(c/m)) \cdot t)\}$

$\text{Return}(mt) \rightarrow \emptyset$

NB: Class fields are strongly typed, holding always only one single type (differently from reg and opd). Unlike the DefensiveVM, VerifyVM therefore uses the declared type of the global field (stored as instr param).

Similarly for class meth invocs, the declared return type is propagated.

Return instrs generate no successor (in the method they leave)

Link-time checkable requirements on objects & their initialization

Fig. 16.14 Successors for JVM_O instructions

$succ_O(meth)(instr, pc, regT, opdT) =$
 $succ_C(meth)(instr, pc, regT, opdT) \cup$

case *instr* **of**

New(*c*) $\rightarrow \{(pc + 1, regS, opdS \cdot [(c, pc)_{new}])\}$

where $regS = \{(x, t) \mid (x, t) \in regT, t \neq (c, pc)_{new}\}$

$opdS = [\text{if } t = (c, pc)_{new} \text{ then unusable else } t \mid t \in opdT]$

GetField(*t, c/f*) $\rightarrow \{(pc + 1, regT, drop(opdT, 1) \cdot t)\}$

PutField(*t, c/f*) $\rightarrow \{(pc + 1, regT, drop(opdT, 1 + size(t)))\}$

InvokeSpecial(*t, c/m*) \rightarrow

let $opdT' = drop(opdT, 1 + argSize(c/m)) \cdot t$

if $methNm(m) = \langle \text{init} \rangle$ **then**

case $top(drop(opdT, argSize(c/m)))$ **of**

$(c, o)_{new} \rightarrow \{(pc + 1, regT[c/(c, o)_{new}], opdT'[c/(c, o)_{new}])\}$

InInit \rightarrow **let** $c/_ = meth$

$\{(pc + 1, regT[c/InInit], opdT'[c/InInit])\}$

else

$\{(pc + 1, regT, opdT')\}$

InvokeVirtual(*t, c/m*) \rightarrow

let $opdT' = drop(opdT, 1 + argSize(c/m)) \cdot t$

$\{(pc + 1, regT, opdT')\}$

InstanceOf(*c*) $\rightarrow \{(pc + 1, regT, drop(opdT, 1) \cdot [\text{int}])\}$

Checkcast(*t*) $\rightarrow \{(pc + 1, regT, drop(opdT, 1) \cdot t)\}$

To guarantee uniqueness of new (uninitialized) objects, delete uninitialized types from reg (to become unavailable at succ) and replace them in opd by unusable

addg
target
object
type
cond

After exec of inst initialzn meth, obj becomes fully initialized

For partly initialzd objs, fully initialzd type is the c of curr initialzn meth

Determining handler frames for successors of JVM_E instrs

Fig. 16.15 Successors for JVM_E instructions

$succ_E(meth)(instr, pc, regT, opdT) =$
 $succ_O(meth)(instr, pc, regT, opdT) \cup allhandlers(instr, meth, pc, regT) \cup$
case *instr* of

Athrow $\rightarrow \emptyset$ Every handler in exception table yields a possible successor

Jsr(*s*) $\rightarrow \{(s, regT, opdT \cdot [retAddr(s)])\}$

Ret(*x*) $\rightarrow \emptyset$

Ret taken into account by defn of type assignment, with types of local vars propagated both from the subroutine return index and from successor index of subroutine call

We assume *Jsr*(), *Goto*(), *Return*(), *Load*(,), which are used for the compilation of abruptio (jump and return) stms, not to throw exceptions so that $allhandlers(instr, m, pc, regT) = \emptyset$, otherwise we include into successors all handlers which protect the code index (for $instr = code(pc)$):

$allhandlers(instr, m, pc, regT) =$

$\{(h, regT, [t]) \mid (f, u, h, t) \in excs(m) \ \& \ f \leq pc < u\}$

Type reg/opd propagation to successors

propagateVM_I (code, succ, pc) =

forall (s, regS, opdS) ∈

succ(code(pc), pc, regV_{pc}, opdV_{pc})

propagateSucc(code, s, regS, opdS)

Adding constraints for excs & embedded subroutines

propagateVM_E (code, succ, pc) =

propagateVM_I (code, succ, pc)

propagateJsrrRet(code, succ, pc)

Propagating type frames (regS,opdS) computed by succ to successor code indices s

propagateSucc(code, s, regS, opdS) =

if $s \notin \text{dom}(\text{visited})$ **then**

For not-yet-visited instrs copy computed frame, but:

if *validCodeIndex*(code, s) **then**

$\text{reg}V_s := \{(x, t) \mid (x, t) \in \text{reg}S, \text{validReg}(t, s)\}$

$\text{opd}V_s := [\text{if } \text{validOpd}(t, s) \text{ then } t \text{ else unusable} \mid t \in \text{opd}S]$

visited(s) := *True*

changed(s) := *True*

restrict retAddr-types in reg and opd to valid ones

else

halt := "Verification failed (invalid code index)"

elseif $\text{reg}S \sqsubseteq_{\text{reg}} \text{reg}V_s \wedge \text{opd}S \sqsubseteq_{\text{seq}} \text{opd}V_s$ **then**

skip

No more verifcn if newly compd types more specific than already assignd ones

elseif $\text{length}(\text{opd}S) = \text{length}(\text{opd}V_s)$ **then**

$\text{reg}V_s := \text{reg}V_s \sqcup_{\text{reg}} \text{reg}S$

$\text{opd}V_s := \text{opd}V_s \sqcup_{\text{opd}} \text{opd}S$

Merge opd stacks (of same length) and registers

changed(s) := *True*

else

halt := "Propagate failed"

Each merge reduces the number of regs with assigned type or introduces a new reg with type unusable, so that if no failure is detected, dom(changed) gets empty

validReg(retAddr(*l*), *pc*) = $pc \in \text{belongsTo}(l)$

validReg(*t*, *pc*) = *True*

validOpd(retAddr(*l*), *pc*) = ($l = pc$)

validOpd(*t*, *pc*) = *True*

retAddrs occur in regs only within subroutines, on stack only at its start

Propagating type frames upon return to direct successors $j+1$ of any (reachable) j from where subroutine s can be entered

$\text{propagateJsrRet}(\text{code}, \text{succ}, \text{pc}) =$

case $\text{code}(\text{pc})$ **of**

$\text{Jsr}(s) \rightarrow \text{enterJsr}(s) := \{\text{pc}\} \cup \text{enterJsr}(s)$ update enterJsr(s)

propagate to $\text{pc}+1$
types from correspondg
subroutine returns i

forall $(i, x) \in \text{leaveJsr}(s), i \notin \text{dom}(\text{changed})$

if $\text{reg}V_i(x) = \text{retAddr}(s)$ **then**

$\text{propagateJsr}(\text{code}, \text{pc}, s, i)$

$\text{Ret}(x) \rightarrow \text{let } \text{retAddr}(s) = \text{reg}V_{\text{pc}}(x)$ update leaveJsr(s)

$\text{leaveJsr}(s) := \{(\text{pc}, x)\} \cup \text{leaveJsr}(s)$

propagate types to $j+1$
for each corresponding
subroutine entry j

forall $j \in \text{enterJsr}(s), j \notin \text{dom}(\text{changed})$

$\text{propagateJsr}(\text{code}, j, s, \text{pc})$

enterJsr(s) = the set of visited indices of instrs $\text{Jsr}(s)$

leaveJsr(s) = set comprising all visited indices of instrs

$\text{Ret}(x)$ which assign type $\text{retAddr}(s)$ to reg x

both functions are initialized in initVerify by \emptyset

Propagating types to direct successor $j+1$ of a subroutine call $Jsr(s)$

$$\begin{aligned} \text{propagateJsr}(\text{code}, j, s, i) = \\ \text{propagateSucc}(\text{code}, j + 1, \text{regJ} \oplus \text{mod}(s) \triangleleft \text{reg}V_i, \text{opd}V_i) \text{ where} \\ \text{regJ} = \{(x, t) \mid (x, t) \in \text{mod}(s) \triangleleft \text{reg}V_j, \\ \text{validJump}(t, s) \wedge t \neq (_, _)_{\text{new}} \wedge t \neq \text{InInit}\} \end{aligned}$$

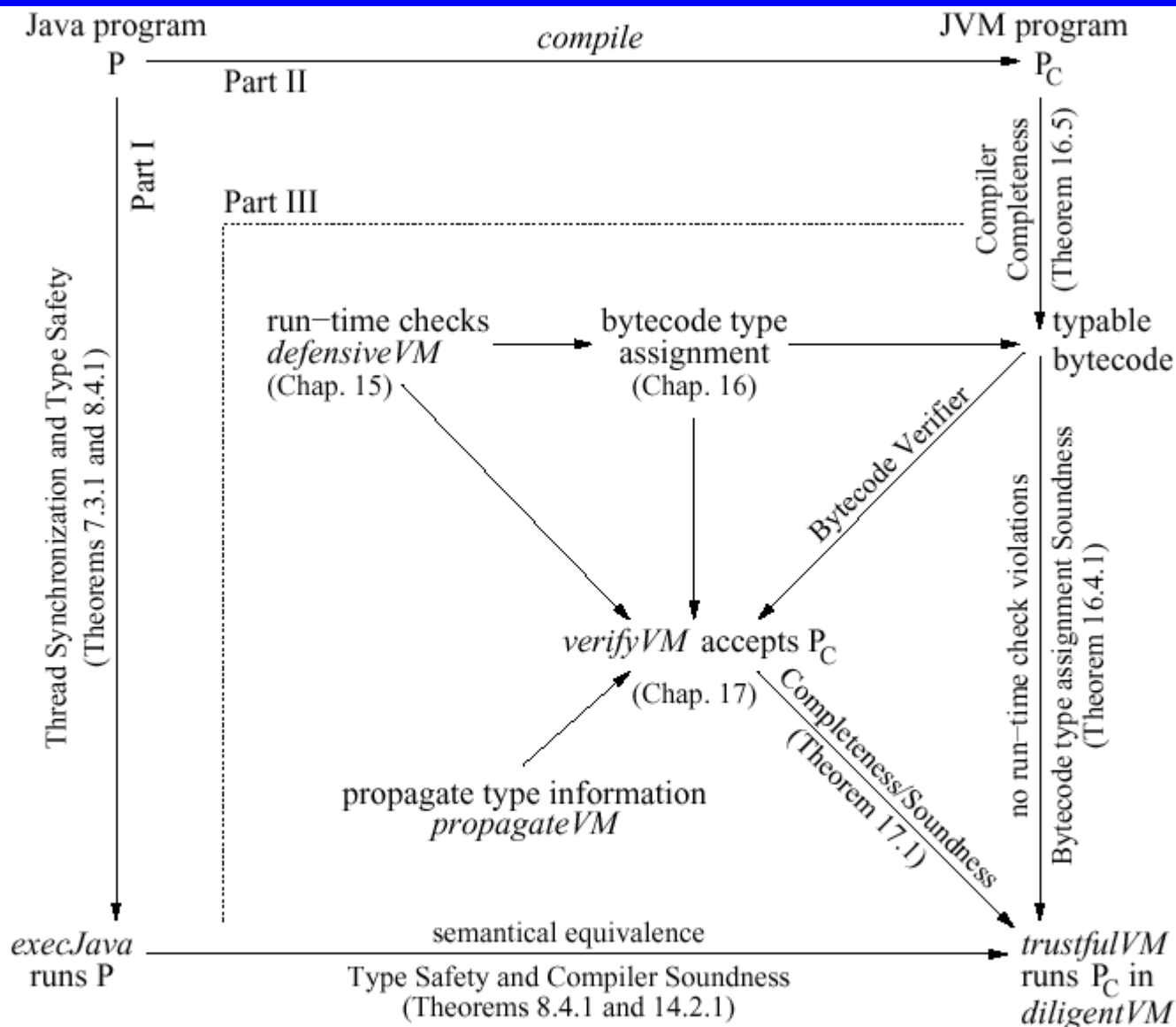
$$\begin{aligned} \text{validJump}(\text{retAddr}(l), s) &= \text{belongsTo}(s) \subseteq \text{belongsTo}(l) \\ \text{validJump}(t, s) &= \text{True} \end{aligned}$$

- a) Restrict registers from the caller frame at j , which have not been modified by the subroutine s but will be used at $j+1$:
 - for proper nesting of subroutines: to `validJump` types – i.e. of addresses of enclosing subroutines,
 - for uniqueness of new (uninitialized) objects: to those of completely initialized objects.
- b) Restrict registers from the return frame, which will be used at $j+1$, to those which have been modified by the subroutine s .

Proving Bytecode Verifier Complete and Correct

- **Bytecode Verifier Soundness Theorem:** For any program P , the Bytecode Verifier either rejects P or during the verification satisfies the type assignment conditions for P .
- **Bytecode Verifier Completeness Theorem:** If P has a type assignment, then the Bytecode Verifier does not reject P and computes a most specific type assignment.

Synopsis of machine decomposition and proof structuring



Dependency Graph of the book chapters

Dynamic Loading (finding binary form) & Linking (preparation and verification) integrated into run-time

by extension execVM_D for loader meths & switchVM_D to reference loaded classes and superclasses before linking

Classes extended by loader, which provides name space (for all types):

$\text{Class} = (\text{Ld}, \text{Name})$

$\text{ldEnv}:\text{Class} \rightarrow \text{Ref}$ yields the class object loaded by given loader under given name

$\text{cOf}:\text{Ref} \rightarrow \text{Class}$ yields the class name with its defining (maybe \neq initiating) loader

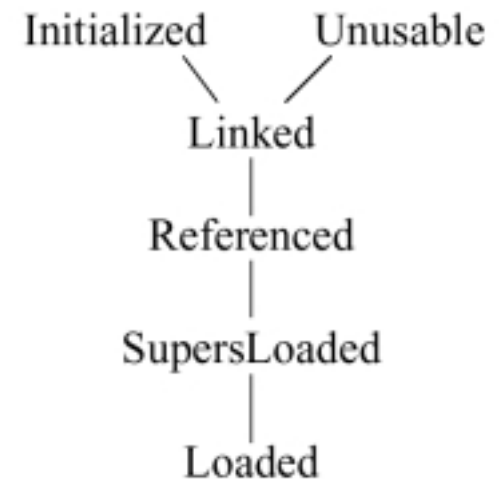
$\text{liftClass}(c) = \text{cOf}(\text{ldEnv}(c))$ yields the defining loader

$\text{cEnv}:\text{Class} \rightarrow \text{ClassFile}$ dynamic fct

$\text{classState}(c)=\text{Loaded}$ means c is loaded

$\text{classState}(c)=\text{SupersLoaded}$ means all superclasses loaded with $\text{classState} \geq \text{SupersLoaded}$

$\text{classState}(c)=\text{Referenced}$ means all superclasses have $\text{classState} \geq \text{Referenced}$ and all referenced classes have $\text{classState} \geq \text{SupersLoaded}$



Task: guarantee the complete availability of all types which may occur during execution of a loaded class

g. 18.2 Refinement of the switch machine

```
switch VMD =  
  switch VME  
  case switch of  
    InitClass(c) → if classState(c) < Referenced then  
                    referenceClass(c)  
    Result(res) →  
      if methNm(meth) = "<clload>" then  
        ldEnv(reg(0), stringOf(reg(1))) := res(0)
```

Strategy: classState(c) gets Referenced only when all superclasses are \geq Referenced and all referenced classes are in state \geq SupersLoaded

Upon return from loader reg(0), store the loaded class obj res(0) under name in reg(1)

```
referenceClass(c) =  
  if c = Object then  
    classState(c) := Referenced  
  elseif classState(c) = SupersLoaded then  
    let supers = {super(c)}  $\cup$  implements(c)  
    choose c'  $\in$  supers, classState(c') < Referenced  
    referenceClass(c')  
  ifnone  
    loadReferences(c)  
  else loadSuperClasses(c)
```

1. reference all superclasses

2. load all referenced classes

load all superclasses if class is loaded only

recursion terminates since class hierarchy is finite

Implicit call $\text{Load}(ld, cn) = (\text{switch} := \text{Call}(\langle \text{cload} \rangle, [ld, cn]))$

Fig. 18.3 Loading super classes and references

```
loadClasses(cs, m) =  
  choose  $c \in cs \setminus \text{dom}(ldEnv)$   
    callLoad(c)  
  ifnone  
    choose  $c \in cs, \text{classState}(\text{liftClass}(c)) = \text{Loaded}$   
      loadSuperClasses(liftClass(c))  
    ifnone m
```

<clod> (String) calls the possibly user defined loadClass method

Load(addr, 0) loader
Load(addr, 1) class name
InvokeVirtual
(Class,loadClass(String))
Return(addr)

```
loadSuperClasses(c) =  
  loadClasses({super(c)}  $\cup$  implements(c), setSupersLoaded(c))
```

after having loaded all superclasses

```
loadReferences(c) =  
  loadClasses(directReferences(c), loadIndirectReferences(c))
```

Similarly for references: 1. load direct refs, 2. load indirect refs,

```
setSupersLoaded(c) =  
  classState(c) := SupersLoaded  
  setDefiningLoadersForSupers(c)
```

set classState to SupersLoaded and replace loader of superclasses in the class file by the defining loader

```
loadIndirectReferences(c) =  
  loadClasses(indirectReferences(c), setReferenced(c))
```

```
setReferenced(c) =  
  classState(c) := Referenced  
  setDefiningLoaders(c)
```

3. set classState to Referenced and replace loader component in the class file by the defining loader

Indirect Refs: classes which appear in context of other refs

g. 18.4 Trustful execution of JVM_D instructions

```
exec  $VM_D =$   
  exec  $VM_N$   
  if  $c = \text{ClassLoader}$  then  
    exec  $\text{ClassLoader}(m)$   
  elseif  $\text{meth} = \text{Class}/\text{newInstance}()$  then  
     $\text{meth} := c\text{Of}(\text{reg}(0))/\langle\text{newInstance}\rangle()$   
where  $c/m = \text{meth}$ 
```

Extension of $\text{exec}VM_N$ by native methods for

- class loading/resolving
- newInstance to create a new instance for a class object

Refine correspondingly check_N for defensive VM_D and diligent VM_D to recognize also native methods for dynamic loading:

$\text{check}_D(c/m) =$

$c = \text{ClassLoader} \ \& \ m \in \{\text{findLoadedClass}, \text{findSystemClass}, \text{resolveClass}, \text{defineClass}\}$

or $c / m = \text{Class} / \text{newInstance}()$

or $\text{check}_N(c / m)$

Loading attempted by invoked loader, internal loader, non-locally

g. 18.5 Execution of final class loader methods

execClassLoader(m) =

if $m = \text{findLoadedClass}$ **then**
 let $c = (\text{reg}(0), \text{stringOf}(\text{reg}(1)))$

if $c \notin \text{dom}(\text{ldEnv})$ **then**
 $\text{switch} := \text{Result}([null])$

else
 $\text{switch} := \text{Result}([\text{ldEnv}(c)])$

if $m = \text{findSystemClass}$ **then**
 let $c = (\text{sysLd}, \text{stringOf}(\text{reg}(1)))$

if $c \notin \text{dom}(\text{ldEnv})$ **then**
 $\text{loadClass}(\text{classPath}, c)$

elseif $\text{classState}(c) < \text{Referenced}$ **then**
 $\text{referenceClass}(c)$

elseif $\text{classState}(c) = \text{Referenced}$ **then**
 $\text{linkClass}(c)$

else
 $\text{switch} := \text{Result}([\text{ldEnv}(c)])$

Did invoked loader already load the class?

if not, return null; othw return the class ref
the class object already loaded by the
invoked loader under the given name

Is class loadable by internal class loader
from local domain (the system loader)?

- a) load,
- b) reference (loading & linking
all superclasses),
- c) link the class,
- d) return the loaded and
linked class object

Loading attempted by invoked loader, internal loader, non-locally

```
if  $m = \text{defineClass}$  then If no local class was found
  let  $c = (\text{reg}(0), \text{stringOf}(\text{reg}(1)))$ 
  if  $c \notin \text{dom}(\text{ldEnv})$  then Check that class name not already in loader name space
    let  $\text{content} = \text{arrayContent}(\text{heap}(\text{reg}(2)), \text{reg}(3), \text{reg}(4))$ 
     $\text{defineClass}(\text{content}, c, \text{True})$  read bytecode from origin of referenced class & create & return class object (without referencing or linking yet)
  else
     $\text{raise}(\text{"ClassFormatError"})$ 
if  $m = \text{resolveClass}$  then
  let  $r = \text{reg}(1)$  implicitly called before initializing a class
  if  $r = \text{null}$  then
     $\text{raise}(\text{"NullPointerException"})$ 
  else
    let  $c = c\text{Of}(r)$ 
    if  $\text{classState}(c) < \text{Referenced}$  then reference and link the class specified by the ref of the class object
       $\text{referenceClass}(c)$ 
    elseif  $\text{classState}(c) = \text{Referenced}$  then
       $\text{linkClass}(c)$ 
    else
       $\text{switch} := \text{Result}([])$ 
```

Macros for Loading, Defining, and Linking classes

§. 18.6 Loading and linking machines

```
loadClass(classPath, c) =  
  if  $c \notin \text{dom}(\text{load}(\text{classPath}))$  then  
    raise( "ClassNotFoundException" )  
  else  
    defineClass(load(classPath), c, False)
```

Check whether the class exists in the local file system

```
defineClass(content, c, returnClass) =  
  let  $cf = \text{analyze}(\text{content})$   
  if  $\text{classNm}(cf) \neq \text{classNm}(c)$  then  
    raise( "ClassFormatError" )  
  else create  $r$   
    classState(c) := Loaded  
    heap(r)       := Object(Class,  $\emptyset$ )  
    cOf(r)        := c  
    cEnv(c)       := cf  
    ldEnv(c)      := r  
  if returnClass then switch := Result([r])
```

check whether the class name coincides with the expected one

create a new class object and initialize its dynamic functions

Macros for Loading, Defining, and Linking classes

```
linkClass(c) =  
  let classes = {super(c)} ∪ implements(c)  
  if c = Object ∨ ∀ c' ∈ classes : classState(c') ≥ Linked then  
    classState(c) := Linked  
    prepareClass(c)  
  elseif ¬cyclicInheritance(c) then  
    choose c' ∈ classes, classState(c') = Referenced  
      linkClass(c')  
  else  
    halt := "Cyclic Inheritance: " · classNm(c)
```

The recursive submachine *linkClass* terminates because of the finiteness of the class hierarchy.

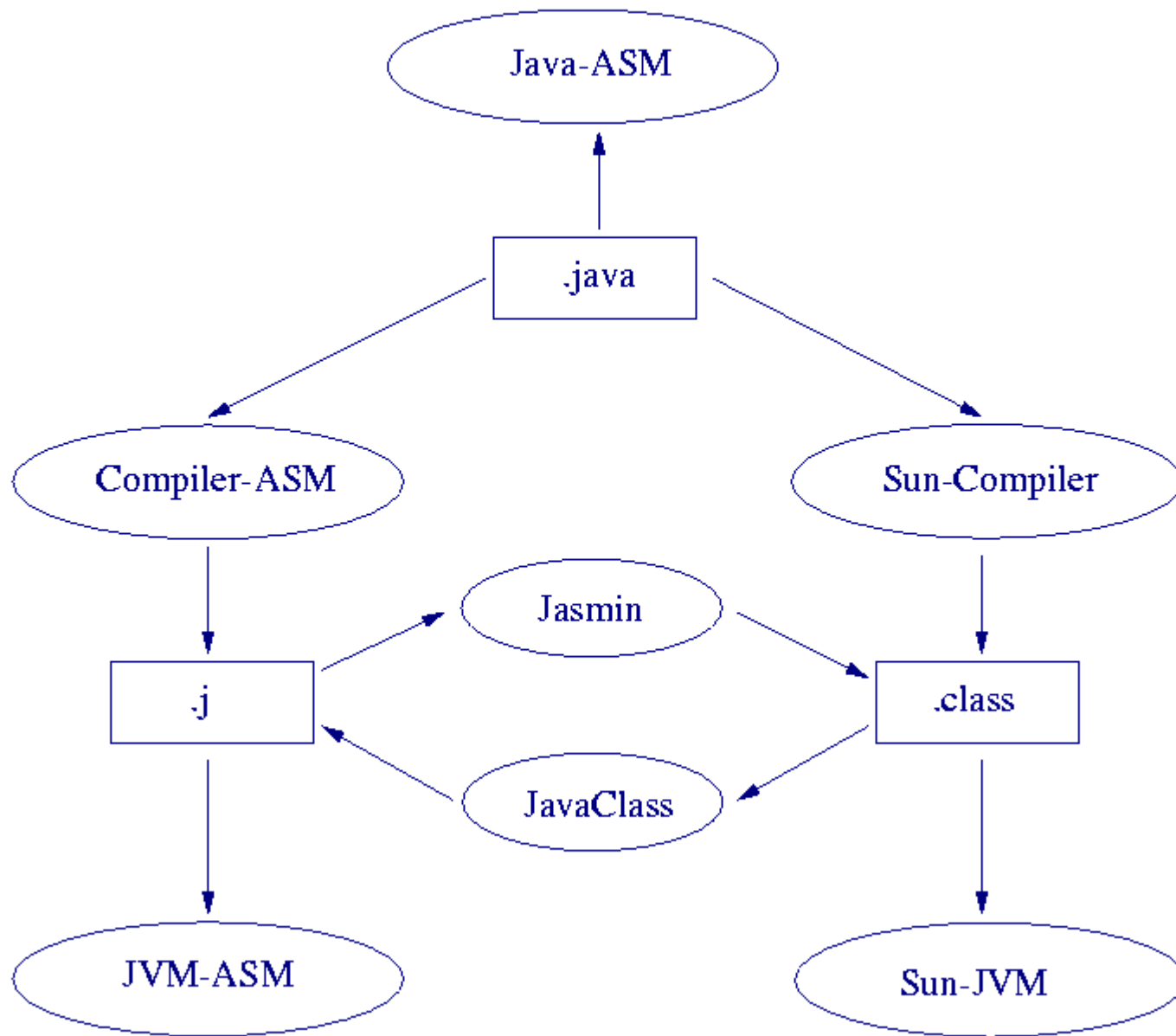
NB. Same machine *linkClass* as in *switchVM_C* except for using only the submachine *prepareClass* of *prepareVerify*:

```
prepareClass(c) = forall f ∈ staticFields(c)
```

```
  globals(c/f) := defaultVal (type(c/f))
```


Validating Java, JVM, compile

- AsmGofer: ASM programming system, extending TkGofer to execute ASMs (with Haskell definable external fcts)
- Provides **step-by-step execution**, with GUIs to support **debugging** of Java/JVM programs.
- Allows for the executable ASM models of Java/JVM:
 - to execute the Java source code P (**no counterpart in SUN env**)
 - to compile Java pgms P to bytecode $\text{compile}(P)$ (in textual representation, using JASMIN to convert to binary class format)
 - to execute the bytecode programs $\text{compile}(P)$E.g. our Bytecode Verifier rejects Saraswat's program
- Developed by Joachim Schmid, available at www.tydo.de/AsmGofer



Reference:

Java and the Java Virtual Machine. Definition, Verification, Validation

R. Stärk, J. Schmid, E. Börger

Springer-Verlag , 2001.

<http://www.inf.ethz.ch/~jbook/>